

Summary

For differential equations of the form $ay'' + by' + cy = 0$, where a, b , and c are constants, we start with the guess $y = e^{rt}$. There are three cases:

Type	Discriminant	General solution
Distinct roots	$\sqrt{b^2 - 4ac} > 0$	$y(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}$
Equal roots	$\sqrt{b^2 - 4ac} = 0$	$y(t) = c_1 e^{rt} + c_2 t e^{rt}$
Imaginary roots	$\sqrt{b^2 - 4ac} < 0$	$y(t) = e^{\alpha t} (c_1 \cos(\beta t) + c_2 \sin(\beta t))$

In the third case, Imaginary roots, we use $r = \alpha \pm \beta i$.

Identification

As the title suggests, use this method for linear second-order homogeneous equations with constant coefficients. These are equations of the form

$$ay'' + by' + cy = 0,$$

where a, b , and c are constants (so no t 's here). For equations of the above form, we assume that our solution takes the form $y = e^{rt}$, where r is a constant for which we must solve (in fact, there are often two r values). Calculating y' and y'' with this assumption and then plugging into the above equation gives

$$ar^2 e^{rt} + bre^{rt} + ce^{rt} = 0,$$

and dividing both sides by e^{rt} (which is never 0) gives

$$ar^2 + br + c = 0.$$

Recall from algebra that this equation has at most two solutions, with

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a},$$

which is the familiar quadratic formula. From here, there are three possibilities: distinct roots, equal roots, and imaginary roots.

Distinct Roots: $b^2 - 4ac > 0$

Consider the equation $y'' + 4y' - 5 = 0$. Using the guess $y = e^{rt}$ and following the reasoning above gives us

$$r^2 + 4r - 5 = 0,$$

which we can solve using the quadratic formula or by factoring the above equation into $(r + 5)(r - 1)$ to get that $r = -5, 1$. We then have two solutions for y :

$$y = e^{-5t} \quad \text{and} \quad y = e^t.$$

These are two linearly independent solutions, so our general solution is

$$y(t) = c_1 e^{-5t} + c_2 e^t,$$

where c_1 and c_2 are arbitrary constants.

Equal Roots: $b^2 - 4ac = 0$

Second-Order Equations: Constant Coefficients

Now consider the equation $y'' - 2y' + y = 0$. This gives us

$$r^2 - 2r + 1 = (r - 1)^2 = 0,$$

so $r = 1$. Thus, $y = e^t$ is one solution. However, we need a second, linearly independent solution. Using the method of reduction of order (in the handout of the same name), we use this first solution to determine that $y(t) = te^t$ is another solution to the above equation. Our general solution then takes the form

$$y(t) = c_1 e^t + c_2 t e^t.$$

Imaginary Roots: $b^2 - 4ac < 0$

Let's now consider the equation $y'' + y = 0$. This gives $r^2 + 1 = 0$. Plugging this into the quadratic formula, with $a = c = 1$ and $b = 0$, gives

$$r = \frac{\pm\sqrt{-4}}{2} = \frac{\pm 2i}{2} = \pm i.$$

This gives us the two solutions $y = e^{it}$ and $y = e^{-it}$, which gives us

$$y(t) = A e^{it} + B e^{-it},$$

where A and B are arbitrary (complex) constants. In order to find real solutions, we must first use Euler's formula:

$$e^{\lambda \pm i\mu} = e^{\lambda t} (\cos(\mu t) \pm i \sin(\mu t)),$$

where λ and μ are real numbers. Here, $\lambda = 0$ and $\mu = 1$, so we get

$$\begin{aligned} y(t) &= A (\cos t + i \sin t) + B (\cos t - i \sin t) \\ &= (A + B) \cos t + (A - B) i \sin t. \end{aligned}$$

Since A and B are arbitrary complex constants, we can actually make the quantities $(A+B)$ and $(A-B)i$ whatever we like, so we may as well replace them with c_1 and c_2 :

$$y(t) = c_1 \cos t + c_2 \sin t.$$

DISCLAIMER: This handout uses notation and methods from the textbook commonly used for M 427J courses taught at the University of Austin: Braun, Martin, *Differential Equations and Their Applications*, 4th ed. Springer

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