

The Method

The method of variation of parameters gives us a general method for solving nonhomogeneous linear second-order differential equations, namely those of the form

$$y'' + p(t)y' + q(t)y = g(t)$$
.

Recall that to find a general solution for a nonhomogeneous equation takes two steps:

- 1. Find a general solution $c_1y_1(t) + c_2y_2(t)$ for the homogeneous equation, y'' + p(t)y' + q(t)y = 0.
- 2. Find a particular solution $\psi(t)$ to y'' + p(t)y' + q(t)y = g(t). Then the general solution is of the form $c_1y_1(t) + c_2y_2(t) + \psi(t)$.

Variation of parameters allows us to find a particular solution $\psi(t)$ given two linearly independent solutions $y_1(t)$ and $y_2(t)$ of the homogeneous equation. If we are given $y_1(t)$ and $y_2(t)$, then our particular solution, $\psi(t)$, will be of the form

$$\psi(t) = u_1(t)y_1(t) + u_2(t)y_2(t)$$

We must figure out $u_1(t)$ and $u_2(t)$. To this end, we use two formulas (not proved here):

$$u_1'(t) = -\frac{g(t)y_2(t)}{W[y_1, y_2](t)}$$
$$u_2'(t) = \frac{g(t)y_1(t)}{W[y_1, y_2](t)},$$

where $W[y_1, y_2](t)$, also called the **Wronskian**, is given by

$$W[y_1, y_2](t) = y_1(t)y'_2(t) - y'_1(t)y_2(t).$$

After computing u'_1 and u'_2 , we can integrate both expressions to get $u_1(t)$ and $u_2(t)$ respectively. We illustrate this with an example.

Example 1. Write the general solution to $y'' + y' - 2y = 4e^{2t}$.

The homogeneous equation is a second-order equation with constant coefficients. We can then compute the complementary solution

$$y_c(t) = Ae^{-2t} + Be^t$$

For the method, we only need two linearly independent solutions, so let's use $y_1(t) = e^{-2t}$ and $y_2(t) = e^t$. With these, we compute the Wronskian:

$$W[y_1, y_2](t) = (e^{-2t}) (e^t) - (-2e^{-2t}) (e^t) = e^{-t} + 2e^{-t} = 3e^{-t}.$$

With $g(t) = 4e^{2t}$, we now compute

$$\begin{aligned} u_1'(t) &= -\frac{g(t)y_2(t)}{W[y_1, y_2](t)} \\ &= -\frac{(4e^{2t})(e^t)}{(3e^{-t})} \\ &= -\frac{4}{3}e^{4t} \\ u_2'(t) &= \frac{g(t)y_1(t)}{W[y_1, y_2](t)} \\ &= \frac{(4e^{2t})(e^{-2t})}{(3e^{-t})} \\ &= \frac{4}{3}e^t \,. \end{aligned}$$

Next, we integrate both of these to get $u_1(t)$ and $u_2(t)$ respectively:

$$\int u_1'(t) dt = -\frac{1}{3} \int 4e^{4t} dt$$
$$= -\frac{1}{3}e^{4t} + D_1$$
$$\int u_2'(t) dt = \frac{4}{3} \int e^t dt$$
$$= \frac{4}{3}e^t + D_2.$$

In fact, these constants of integration are unnecessary. We leave them in to see what happens to themthey will become irrelevant. We now compute

$$\psi(t) = u_1(t)y_1(t) + u_2(t)y_2(t)$$

= $\left(-\frac{1}{3}e^{4t} + D_1\right)\left(e^{-2t}\right) + \left(\frac{4}{3}e^t + D_2\right)\left(e^t\right)$
= $e^{2t} + D_1e^{-2t} + D_2e^t$.

Our general solution is then

$$y(t) = (A + D_1)e^{-2t} + (B + D_2)e^t + e^{2t}.$$

Since A, B, D_1 , and D_2 are all arbitrary constants, we rewrite this as

$$y(t) = c_1 e^{-2t} + c_2 e^t + e^{2t},$$

which is why we could have ignored the constants of integration D_1 and D_2 .

DISCLAIMER: This handout uses notation and methods from the textbook commonly used for M 427J courses taught at the University of Austin:

Braun, Martin, *Differential Equations and Their Applications*, 4th ed. Springer December 5, 1992.