

SETTING ADVANCE ANALYSIS **APPLY** EXIT

4

**OUTPUT**

PROJECT-/FILENAME  
Dab\_Michael 2

OUTPUT DIRECTORY  
BROWSE 3

**SPEED**

PTP initial speed  
100 [0-100] %

LIN initial speed  
0.5 [0.0-2.0] m/s

**SIMULATION**

Smooth Robot Simulation  
 Simulate Without KRL Generation  
 Collision Checking

Speed Optimizer:  
Custom

**DATA**

INPUT COMMANDS  
9

INITIAL TOOL  
Custom Tool Nr. 2

ROBOT TYPE  
KUKA KR30/KR60/KR60HA series

KUKA|PRC VERSION  
2016-03-31

LICENSED TO  
TRIAL USER

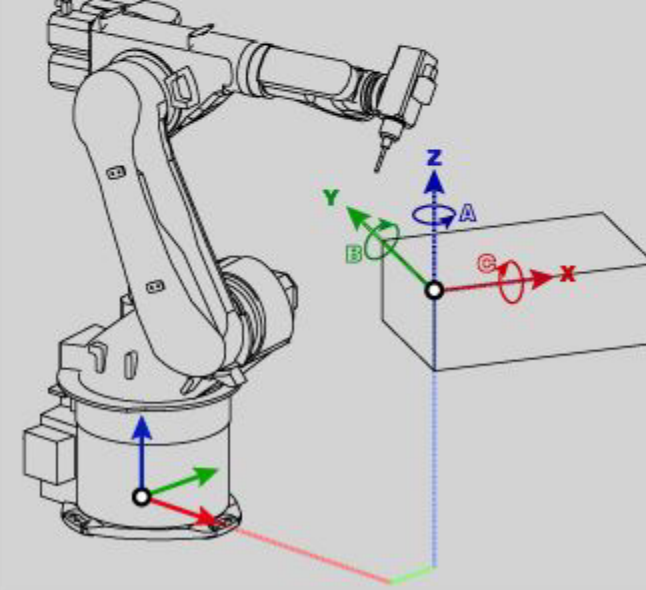
TRIAL VERSION - SOME FEATURES ARE LOCKED

**KUKA|prc**

**BASE**

Base Nr. 4

Base X -75.001  
Base Y -1638.989  
Base Z 492.168  
Base A 0  
Base B 0  
Base C -0.453



**1**

